

2019_03_07_11.27__Fazio_Sandri.txt

<http://zerorobotics.mit.edu/ide/simulation/3685505/>

Fuel:74% **Thruster Health:100 (SOPRA) Score: 7.573**
 DEB Fuel: 85% Score:2.500 45s
 RV Fuel: 74% Score:7.570 100s

Sphere 1, 99.0s, GT: Rendezvous complete! Bonus points awarded: 2.361
 Sphere 1, 100.0s, GT: PHASE 2 complete in 55 seconds! 2.708 points gained!

2019_03_07_11.16__Schmitt.cpp

<http://zerorobotics.mit.edu/ide/simulation/3685506/>

Fuel:70% **Thruster Health:75 (SOTTO) Score: 7.671**
 DEB Fuel: 84% Score:2.500 47s
 RV Fuel: 72% Score:7.658 97s

Sphere 1, 96.0s, GT: Rendezvous complete! Bonus points awarded: 2.283
 Sphere 1, 97.0s, GT: PHASE 2 complete in 51 seconds! 2.875 points gained!

submit: 11:16 giov 7 marzo Score giornaliero max: 7.74

2019_03_01_09.51__Schmitt_Corsi_project_1.cpp

<http://zerorobotics.mit.edu/ide/simulation/3680275/>

Fuel:89% Score:3.583 **Thruster Health:25 collisions** Fuel:69% Score:-2.417
 RV Fuel:46% Score:2.356 Fuel:45% **Score: 2.366**

Sphere 1, 191.0s, GT: Rendezvous complete! Bonus points awarded: 2.273

Sphere 1, 192.0s, GT: **PHASE 2 complete in 175 seconds! 2.500 points gained!**

Sphere 1, 209.0s, GT: BONUS: Target Y Distance of 0.0094 [Target Y_final = -0.4977]

2019_03_01_09.48__Ricciolini_Parisi.txt

<http://zerorobotics.mit.edu/ide/simulation/3680276/>

Fuel:89% Score:3.58 **Thruster Health:0 collisions** **Score:2.836**

<http://zerorobotics.mit.edu/ide/simulation/3680277/>**Thruster Health:0**

2019_03_01_09.47__Gioia_Quaranta.txt

<http://zerorobotics.mit.edu/ide/simulation/3680278/>

Fuel:90% Score:3.500 **Thruster Health:25** Fuel:41% **Score:3.497**

2019_03_01_09.42__Pisana_Angelucci.cpp

<http://zerorobotics.mit.edu/ide/simulation/3680280/>

Fuel:94% (in 37s in pX:0.001, pY:0.752, pZ:0.601)

Fuel:85% Score:2.500 Thruster Health:100 in 55s

Collisions SEMPRE Fuel:70% Score:-5.500 Fuel:67% **Score:-16.989**

 2019_02_28_15.07__Fazio.txt

<http://zerorobotics.mit.edu/ide/simulation/3675842/>
con **CancelDebris=1**

Fuel:90% Score:3.417

RV Fuel:87% Score:9.149**Score: 9.156**

Sphere 1, 56.0s, GT: Rendezvous complete! Bonus points awarded: 2.315

Sphere 1, 57.0s, GT: PHASE 2 complete in 38 seconds! 3.417 points gained!

<http://zerorobotics.mit.edu/ide/simulation/3675840/>
Fuel:89% Score:3.583 **Thruster Health:5** (poi 0 per Fuel:0%)**Score: 3.604**
<http://zerorobotics.mit.edu/ide/simulation/3675838/>
Fuel:88% Score:3.500 **T.Health:40** **RV** Fuel:72% Score: 9.230**Score: 9.245****Sphere 1, 56.0s, GT: Rendezvous complete! Bonus points awarded: 2.355**Sphere 1, 57.0s, GT: **PHASE 2 complete in 39 seconds! 3.375 points gained!**

Sphere 1, 209.0s, GT: BONUS: Target Y Distance of 0.0154 [Target Y_final = -0.4962]

<http://zerorobotics.mit.edu/ide/simulation/3675836/>
Fuel:87% Score:3.500 **Thruster Health:0****Score: 3.523**

 2019_02_21_15.51__Pisana__Angelucci.cpp

<http://zerorobotics.mit.edu/ide/simulation/3675411/>
va in basso (pX: -0.000 pY: 0.747 pZ: 0.597) **resta in Y+** Fuel:92% **Score: -0.006**Sphere 1, 209.0s, GT: BONUS: Target Y Distance of **-0.0060** [Target Y_final = -0.5015]

 2019_02_21_14.34__Ricciolini__Parisi.txt

<http://zerorobotics.mit.edu/ide/simulation/3675410/>
Fuel:89% Score:3.583 **Thruster Health:25****collisions** Score:**-2.667****RV** Fuel:50% Score:2.183Fuel:50% **Score: 2.195****Sphere 1, 192.0s, GT: Rendezvous complete! Bonus points awarded: 2.349**Sphere 1, 193.0s, GT: **PHASE 2 complete in 176 seconds! 2.500 points gained!**

Sphere 1, 209.0s, GT: BONUS: Target Y Distance of 0.0124 [Target Y_final = -0.4969]

 2019_02_21_14.29__Corsi__Quaranta.txt

<http://zerorobotics.mit.edu/ide/simulation/3675408/>
Fuel:85% Score:3.667 **Thruster Health:15** (poi 0 per Fuel:0%)**Score:3.679**

Sphere 1, 209.0s, GT: BONUS: Target Y Distance of 0.0128 [Target Y_final = -0.4968]

<http://zerorobotics.mit.edu/ide/simulation/3675409/>
Fuel:85% Score:3.667 **Thruster Health:0** OUT OF BOUNDS**Score:3.683**

Sphere 1, 209.0s, GT: BONUS: Target Y Distance of 0.0167 [Target Y_final = -0.4958]

<http://zerorobotics.mit.edu/ide/simulation/3675412/>
con **CancelDebris=1**

Fuel:86% Score:3.583 (pX:0.306 pY:-0.310 pZ:0.506)

Fuel:78% **Score:3.597**

Sphere 1, 209.0s, GT: BONUS: Target Y Distance of 0.0132 [Target Y_final = -0.4967]

<http://zerorobotics.mit.edu/ide/simulation/3675413/>
con **CancelDebris=1**

Fuel:86% Score:3.583 (pX:0.295 pY:-0.302 pZ:0.511)

Fuel:79%..**Score:3.585**

Sphere 1, 209.0s, GT: BONUS: Target Y Distance of 0.0013 [Target Y_final = -0.4997]

<http://zerorobotics.mit.edu/ide/simulation/3675414/>
Fuel:84% Score:3.583 **Thruster Health:15** (**collision???**) Fuel:0% **Score:3.602**

Sphere 1, 209.0s, GT: BONUS: Target Y Distance of 0.0188 [Target Y_final = -0.4953]

2019_02_21__12.48__Fazio_Sandri_3.txt

<http://zerorobotics.mit.edu/ide/simulation/3674713/>

va in alto e pendola (pX:-0.002 pY:0.752 pZ:-0.473) (resta in Y+) Fuel:91% **Score:0.016**

2019_02_21__12.23__Maffei.txt

<http://zerorobotics.mit.edu/ide/simulation/3675407/>

Fuel:88% Score:3.583 **Thruster Health:25**

collisions Score:-2.667(Fuel:68%) **RV** Fuel:42% Score:2.090 **Score:2.117**

Sphere 1, 191.0s, GT: Rendezvous complete! Bonus points awarded: 2.257

Sphere 1, 192.0s, GT: **PHASE 2 complete in 175 seconds! 2.500 points gained!**

Sphere 1, 209.0s, GT: BONUS: Target Y Distance of 0.0269 [Target Y_final = -0.4933]

submit: 11:27 ven 1 marzo

Score giornaliero max: 5.65

2019_02_14__12.05__Pisana_Fazio.cpp

<http://zerorobotics.mit.edu/ide/simulation/3674714/>

Fuel:90% Score: 3.833 **Thruster Health:50**

va dritto, non si ferma OUT of BOUNDS **Score: 3.590**

2019_02_14__11.42__Quaranta_Gioia.cpp

<http://zerorobotics.mit.edu/ide/simulation/3674715/>

Fuel:89% Score:3.750 **Thruster Health:15** (Fuel:0% quindi **collisions**) **Score: -1.732**

<http://zerorobotics.mit.edu/ide/simulation/3674716/>

Fuel:89% Score:3.750 **Thruster Health:50**

Score: 3.754

2019_02_14__11.11__Pisana_Fazio.cpp

<http://zerorobotics.mit.edu/ide/simulation/3665746/>

<http://zerorobotics.mit.edu/ide/simulation/3665754/>

submit: 11:02 giov 14 febbraio

Score giornaliero max: 3.76
