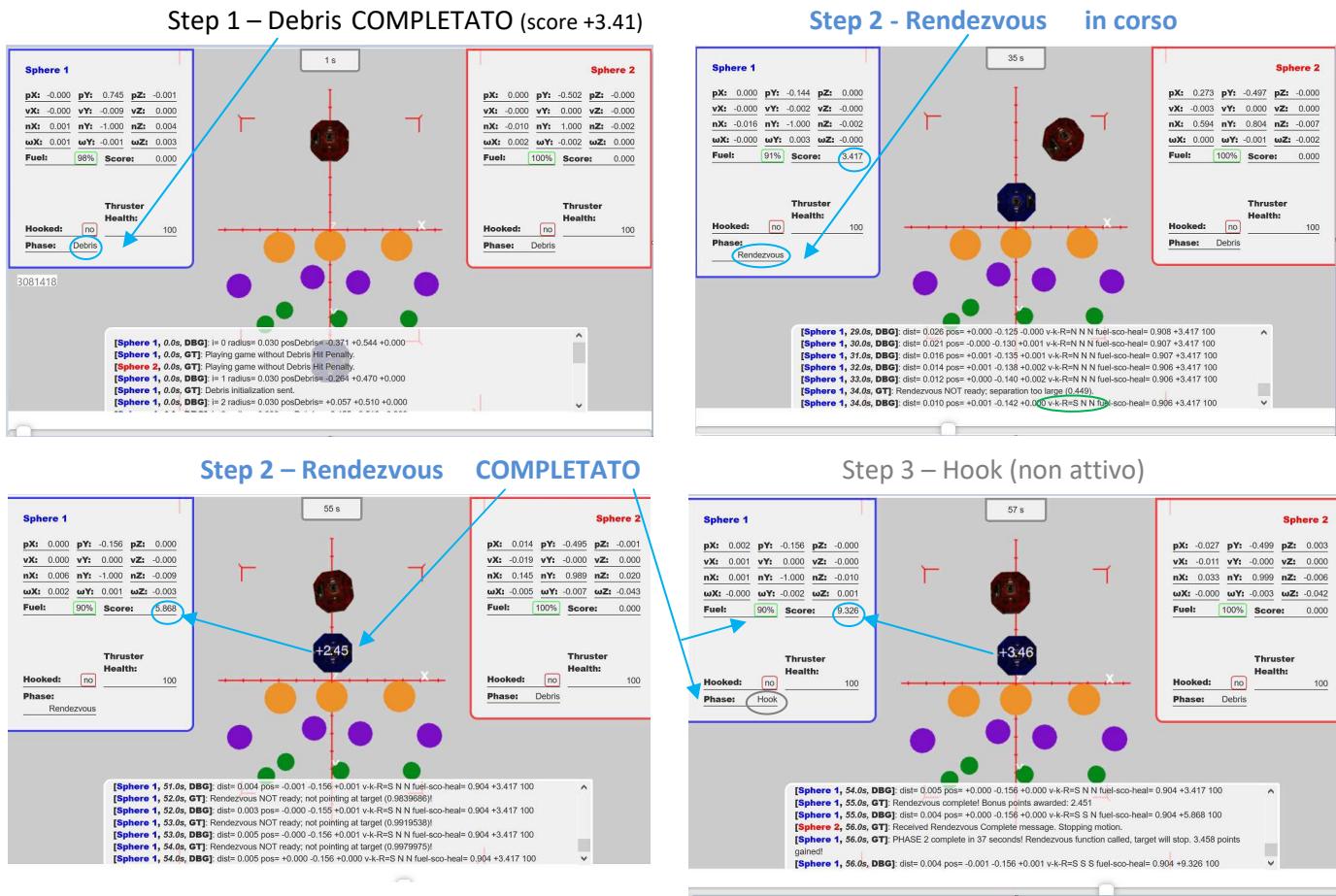


## Step 1 --- Step 2



Simulazione da 100 secondi con `cancelDebris` impostato ad 1

```

Sphere 1, 0.0s, DBG: i = 0 radius= 0.030 posDebris= -0.371 +0.544 +0.000
Sphere 1, 0.0s, DBG: i = 1 radius= 0.030 posDebris= -0.264 +0.470 +0.000
Sphere 1, 0.0s, DBG: i = 2 radius= 0.030 posDebris= +0.057 +0.510 +0.000
Sphere 1, 0.0s, DBG: i = 3 radius= 0.030 posDebris= +0.455 +0.518 +0.000
Sphere 1, 0.0s, DBG: i = 4 radius= 0.045 posDebris= -0.523 +0.329 +0.000
Sphere 1, 0.0s, DBG: i = 5 radius= 0.045 posDebris= -0.108 +0.275 +0.000
Sphere 1, 0.0s, DBG: i = 6 radius= 0.045 posDebris= +0.166 +0.301 +0.000
Sphere 1, 0.0s, DBG: i = 7 radius= 0.045 posDebris= +0.553 +0.312 +0.000
Sphere 1, 0.0s, DBG: i = 8 radius= 0.090 posDebris= -0.294 +0.102 +0.000
Sphere 1, 0.0s, DBG: i = 9 radius= 0.090 posDebris= -0.007 +0.092 +0.000
Sphere 1, 0.0s, DBG: i = 10 radius= 0.090 posDebris= +0.384 +0.092 +0.000

```

19s **PHASE 1 complete** in 19 seconds! Debris area passed (but debris IS still present). **3.417 points gained!**

34s **RAGGIUNTO il punto per Rendezvous**

Sphere 1, 34.0s, DBG: dist= 0.010

54s, Rendezvous NOT ready; not pointing at target (0.9979975)!

55s **checkRendezvous() OK**

Sphere 1, 55.0s, GT: Rendezvous complete! Bonus points awarded: **2.451**

56s **PHASE 2 complete** in 37 seconds! Rendezvous function called, **target will stop**. **3.458 points** gained!

**SPHERES 2 Received Rendezvous Complete message. Stopping motion.**

Sphere 1      dist= 0.004 .... v-k-R=S S S fuel-sco-heal= 0.904 +9.326 100

v-k-R=S S S significato (valori: S per SI , N per NO):

<b>v</b>	<b>VICINO</b>
<b>k</b>	<i>checkRendezvous()</i> è vero
<b>R</b>	<i>completeRendezvous()</i> è vero

<b>S (SI)</b>	
<b>S (SI)</b>	condizioni rispettate per il Rendezvous
<b>S (SI)</b>	Rendezvous completato

Ma, subito dopo, riprende a segnalare:

57.0s, **Rendezvous NOT ready; not pointing at target (0.9954552)!** (**RED non può fermarsi istantaneamente !!**)